User Manual

Lynx-GigE

Lynx-CL

ENG-2012-UMN018-R004

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Doc Ref: ENG-2012-UMN018
Issue: 004
Date: 08/01/2015
XF-104_02/20-01-2012

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Revision History

Issue	Issue date	Reason for changes	Modified by	Approved by
000.01	05/09/2012	Creation of document, starting from ENG-2012-ICD010	JDS/CDU	
000.02	07/09/2012	Updated according to review BVH, JSN	CDU	
000.03	18/03/2013	Chap. 10 Conversion Gain Factor to Feedback Capacitor added (input JBT)	CDU	
000.04	22/04/2013	Figures 2.1 and 2.2 updated, appendices added, chapters deleted: Network connection for GigE, Registers, XSP protocol, Image processing, which are in the appendices now	CDU	
000.05	03/05/2013	Table 3.1: new standard lenses added and rest updated	CDU	
000.06	19/07/2013	Small corrections	BVF	
000.07	03/09/2013	Frame rate calculator added	JDS	
001	03/09/2013	Table 3.1 lenses updated. First released issue	CDU	JDS
001.01	17/10/2013	All technical drawings put in one Appendix, interfaces put together in 1 table	CDU	JDS
001.02	06/11/2013	New issue of the Frame rate calculator added in Appendix	CDU	JDS
001.03	14/11/2013	CL interface: note added about the timing diagram	CDU	JDS
001.04	06/01/2014	Trigger warning added	CDU	JDS
001.05	16/01/2014	New mechanical drawing	JDH	JDS
001.06	21/01/2014	Updated Ref 6 Xeneth Installation Manual	CDU	JDS
001.07	23/02/2014	Getting started added	JDS	CDU
001.08	25/02/2014	Quantum Efficiency added	JDS	CDU
001.09	27/02/2014	Stingray lens removed, spectral band updated and dark current added Max. Storage Temperature added	CDU	JDS
002	03/03/2014	New issue of XLIN-TE0 Control & Operation in Appendix Second released issue	CDU	JDS
003	31/03/2014	Appendix mechanical drawing updated (EASM file removed) Third released issue.	CDU	JDS
003.01	18/06/2014	Update List of Abbreviations	JDS	JDS
003.02	04/11/2014	Update for the CD-packs in Navision: chap.7: appendices titles changed	CDU	JDS
003.03	05/01/2015	Cameras with rectangular pixels added Adjustable clipping feature added	JDS	KNB
004	08/01/2015	Fourth released issue	KNB	JDS

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Change Details

This table lists all changes of this issue compared to the previous released one.

Chapter/Section	Changes	Modified by

Table of Contents

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List of Abbreviations

ASY	Assembly
CC	Camera Control
CE	Conformité Européenne
CL	Camera Link protocol
CLK	Clock
CTIA	Capacitive Trans Impedance Amplifier
GigE	Gigabit Ethernet
GND	Ground
ICD	Interface Control Document
InGaAs	Indium Gallium Arsenide
OPT	Optics
RECT	Rectangular pixel configuration
RJ	Registered Jack
SDK	Software Development Kit
SDR	Shrunk Delta Ribbon connector
SMA	Sub-Miniature version A connector
SQ	Squared pixel configuration
SW	Software
SWIR	Short-Wave Infrared
TE0	TEC-less
UMN	User Manual
XEN	Xenics Part Number
XLIN	Xenics Linear Detector
XSL	Xenics SWIR Linear Core
XSP	Xenics Serial Protocol

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1. Introduction

1.1. Scope

This User Manual describes the technical specifications, dimensions, image processing, basic and advanced parameters and related subjects for the following cameras:

Camera	Pixel configuration (*)	# pixels	Pixel size [µm²]	Part number
Lynx-512-25um-GigE	SQ	512	25x25	XEN-000309
Lynx-1024-12.5um-GigE	SQ	1024	12.5x12.5	XEN-000310
Lynx-2048-12.5um-GigE	SQ	2048	12.5x12.5	XEN-000311
Lynx-512-25um-CL	SQ	512	25x25	XEN-000312
Lynx-1024-12.5um-CL	SQ	1024	12.5x12.5	XEN-000313
Lynx-2048-12.5um-CL	SQ	2048	12.5x12.5	XEN-000314
Lynx-512R-25um-CL	RECT	512	25x250	XEN-000429
Lynx-512R-25um-GigE	RECT	512	25x250	XEN-000430
Lynx-1024R-12.5um-CL	RECT	1024	12.5x250	XEN-000431
Lynx-1024R-12.5um-GigE	RECT	1024	12.5x250	XEN-000432
Lynx-2048R-12.5um-CL	RECT	2048	12.5x250	XEN-000433
Lynx-2048R-12.5um-GigE	RECT	2048	12.5x250	XEN-000434

Table 1-1 Camera overview – Lynx-GigE and Lynx-CL

(*) SQ = squared, RECT = rectangular

1.2. Reference Documents

(Ref 1) Xenics Serial Protocol ENG-2011-ICD003
(Ref 2) Mechanical Drawings Lynx-512-1024-2048-GigE and CL
(Ref 3) XLIN-TE0 Control&Operation ENG-2013-ICD009
(Ref 4) Framerate Calculator ENG-2013-ICD011
(Ref 5) Network connection set-up for GigE ENG-2013-ICD003
(Ref 6) Xeneth Installation Manual (see Xeneth SW directory): ENG-2013-UMN024

1.3. Manual Overview

This section provides a chapter overview:

- Chapter 1 (this chapter) gives an overview of the conventions used in this manual (styles and symbols), the safety warnings, conformity information about Xenics cameras and the contact information.
- Chapter 2 gives a mechanical (2D drawings) and electrical overview
- Chapter 3 describes how to get started with the camera.
- Chapter 4 describes the optical interfaces
- Chapter 5 describes the electrical interfaces

- Chapter 6 provides the installation of the Xeneth and SDK software
- Chapter 7 lists the appendices.

1.4. Conventions Used in This Manual

To give this manual an easily understood layout and to emphasize important information, the following typographical styles and symbols are used:

The styles used in this manual are:

- **Bold**: used for programs, inputs (commands or parameters) or highlighting important things
- `Courier New:` used for code listings and output.
- *Italics*: used for modes and fields.

The symbols used in this manual:

Note: This symbol highlights important information.

Warning: This symbol highlights important instructions. These instructions must be followed to avoid malfunctions!

1.5. Safety Warnings

The following safety warnings must be followed:

Supply voltage polarity: Use the correct polarity of the 12 V supply voltage.

Warranty: The warranty becomes void in case of unauthorized tampering or any manipulations not approved by the manufacturer.

Electrostatic discharge: The camera contains sensitive electronic components which can be destroyed by means of electrostatic discharge. Use sufficient grounding to minimize the risk of damage.

Environmental conditions: Operate the camera in dry and dust free environment. Regarding the signal quality of the camera it is an advantage to operate the camera under constant ambient air temperature (~20°C).
Beneath or above ambient temperature a sufficient heating or cooling may be necessary.

Warm-up Period: Depending on the prevailing environmental conditions, some time might pass after the camera start, until the image quality reaches its optimum.

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1.6. Conformity

Xenics declares under its sole responsibility that all standard cameras of the Lynx family to which this declaration relates to, are conform with the following standard(s) or other normative document(s):

- CE, following the provisions of 2004/108/EG directive
- RoHS (2002/95/EC).

CE:

We declare, under our sole responsibility, that the previously described Lynx cameras conform to the CE directives.

1.7. Contact Information

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- **Distributors worldwide**
  Xenics is a European based provider of infrared imaging products and has representatives and distributor locations around the world to service our many customers.

  Please visit our website for more contact details:
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2. Mechanical & Electrical Specifications

The mechanical drawings of Lynx-GigE and Lynx-CL can be found in (Ref 2).

2.1. Lynx Detector Specifications

The detector specifications are summarized in Table 2-1:

Feature	Specification	
Array Type	InGaAs	
Spectral Band	0.9-1.7 µm	
Quantum Efficiency	>80% (@ 1600nm)	
# pixels	512 or 1024 or 2048	
Pixel pitch	25 µm (512) or 12,5 µm (1024 and 2048)	
Pixel height	SQ: 12.5 µm (1024 & 2048) or 25 µm (512) RECT: 250 µm	
Sensor gain	16 user selectable gain settings	
Dark current at 25°C sensor temperature (typical value)	SQ & 512	$3x10^6$ [e/s]
	SQ & 1024 / 2048:	$1.5x10^6$ [e/s]
	RECT & 512:	$3x10^7$ [e/s]
	RECT & 1024 / 2048:	$1.5x10^7$ [e/s]
Exposure time range	1 µs – 1s Timer or trigger dependent exposure time	

Table 2-1 Detector specifications

2.2. Lynx-GigE and Lynx-CL Specifications

The camera specifications are listed in Table 2-2.

Feature	GigE	CL
Frame rate (full frame)	40 kHz (for 512 and 1024), 10kHz (for 2048)	
Cooling	No	
A/D conversion resolution	14 bit	
On-board image processing features	Digital fixed gain and digital fixed offset Adjustable Clipping Level	
Electrical interface	GigE Vision (image acquisition and camera control)	Camera Link (image acquisition and camera control)
Power over Ethernet	Yes	No
Trigger	Line and Frame trigger	
Input Voltage	12V±10%	
Power consumption	< 4.6W	< 2.6W
Dimensions	49x49x71 mm^3	49x49x53 mm^3
Weight	208g	153g
Ambient Operating Temperature	-40°C to 70°C	
Storage Temperature	-50°C to 85°C	

Table 2-2 Specifications Lynx-GigE and Lynx-CL cameras

i The design and specifications for the products described above may change without notice.

3. Getting Started

In this section we describe the different steps how to get started easily with the Lynx camera.

3.1. Connect to the Camera using Xeneth

The way to connect the camera to use Xeneth is the following:

- Connect all necessary cables to the camera. For details about the electrical interface and cables: see chap. 5.
- Install Xeneth on the pc. For the Lynx CL, make sure that the framegrabber is installed properly. For more information see chap. 6 & (Ref 6).
- Start Xeneth by clicking the Xeneth shortcut on the desktop to start up Xeneth (see Figure 3-1). The connection dialog will become visible (see Figure 3-2). When the camera is not shown, click the refresh button on the dialog. Select the camera, together with the calibration data suited for it. For more details, consult the Xeneth User Manual, section Connection setup - Settings.

Figure 3-1 Xeneth shortcut

- Select the camera in the Connection Setup window (see Figure 3-2).
- Select the calibration pack to be loaded (see Figure 3-2).
    - To use a calibration pack in software, select the name of the calibration pack (note that calibrations in software can **ONLY** be used for the Lynx-CL).
    - To use the onboard calibration use: <Camera memory>.
    - Press <Connect> to connect to the camera.
- Press <Start Capturing> to start grabbing frames (see Figure 3-3).

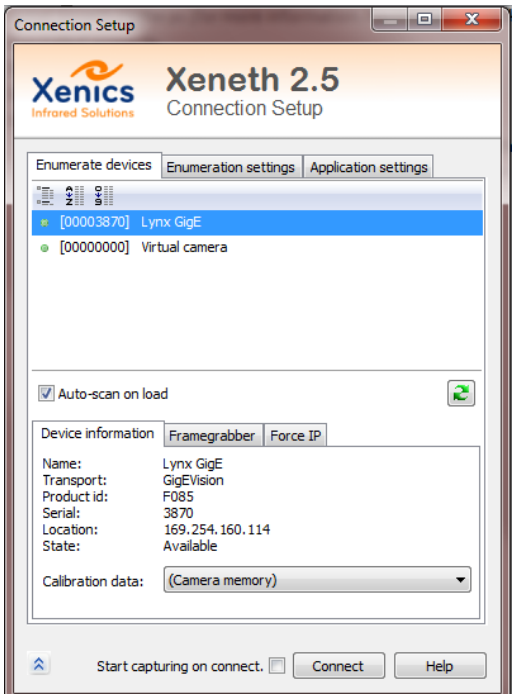

Figure 3-2 Connection setup

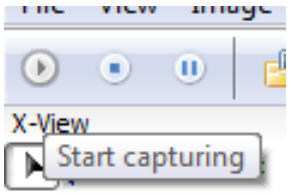

Figure 3-3 Start Capturing

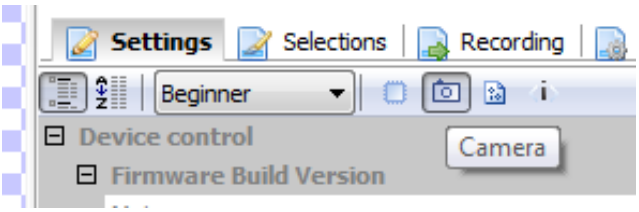

Figure 3-4 Access the camera properties

3.2. Change Camera Properties

Perform the following steps to change the camera properties:

- To change the camera properties, press the <Camera> icon (see Figure 3-4).
- When using the camera for the first time, use the Beginner mode (see Figure 3-4).
- In the beginner mode, the following properties can be modified by the user. For more information on the camera properties, see (Ref 3), or click on the property (Right-button-click) and select <Show property documentation>.

- Device control:
  - Device gain: Value 0 to 15, to set the feedback capacitor value of the CTIA readout. For the values of the capacitor, see (Ref 3).
- Acquisition control
  - Exposure time: Sensor exposure time. Note that a correction file is only valid for 1 exposure time. When the exposure time changes, the offset should be re-calibrated.
- Image format control
  - Height: This value sets the number of lines within a frame.
- Image processing control
  - Offset: This poperty applies a global offset to the image.
  - Gain: This property applies a digital gain to the image
- GigE Vision Transport Layer (only for GigE)
  - Packet Delay

3.3. Use of Correction Files

Perform the following to use the correction files:

- To select a different correction in **software (only for Lynx-CL):** press the <Select> button and select a different correction file.

- To upload and use a **correction file onboard**, perform the following steps:
  - In Xeneth: go to the Settings tab / Storage icon (see Figure 3-5)
  - Upload the correction file:
    - Click on Correction file property and then on the green upload arrow on the right (see Figure 3-6).
    - Select the new correction file.
    - Wait till the file is transferred to the camera (= wait until Xenics logo disappears: see Figure 3-7).
  - Reconnect to the camera to activate the new correction file. While reconnecting, choose ‘camera memory’ calibration data (see Figure 3-8).
- The correction can be enabled and disabled using the **enable image correction button** (see Figure 3-9).

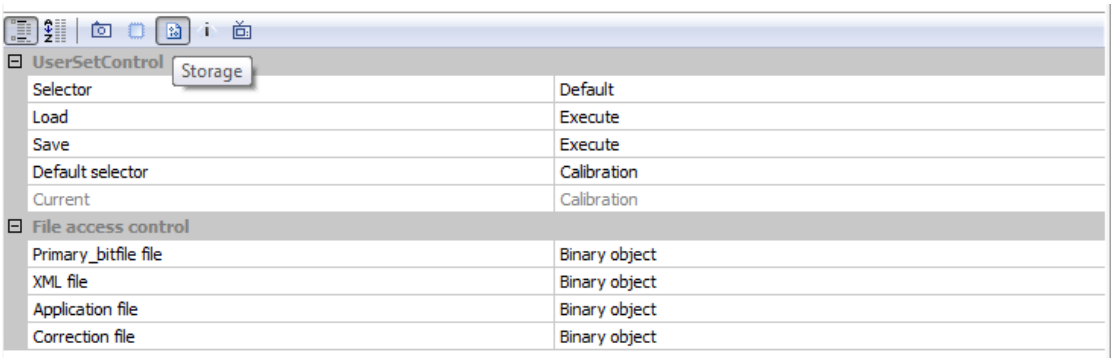

Figure 3-5 Correction pack upload: storage icon

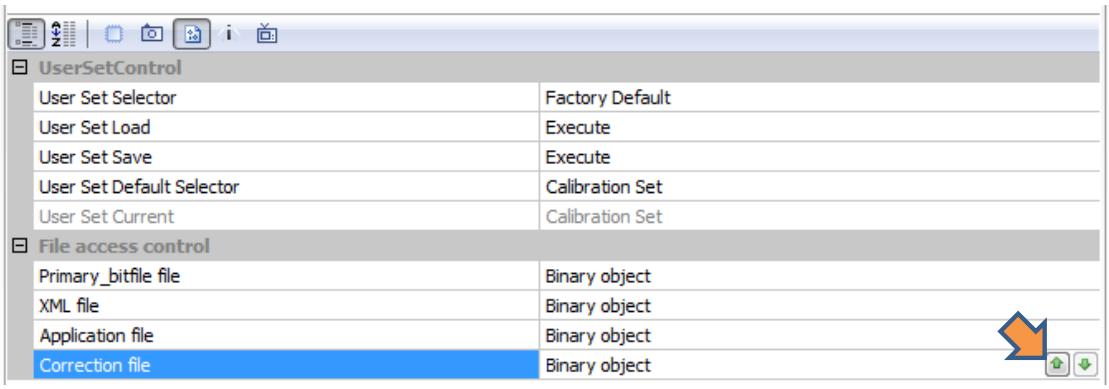

Figure 3-6 Correction file upload

Figure 3-7 Xenics logo while correction file upload

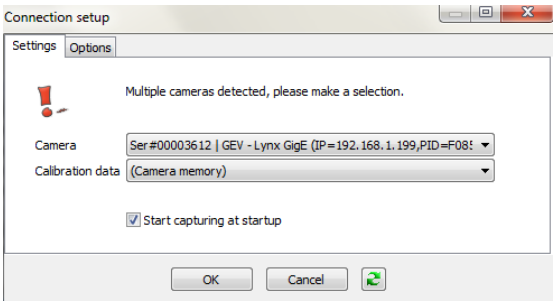

Figure 3-8 Reconnect to camera with onboard correction

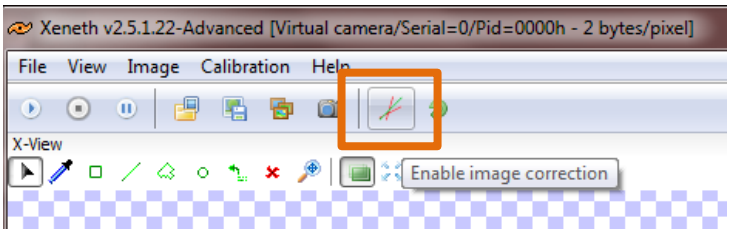

Figure 3-9 Enable image correction

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4. Optical Interface

The optical interface of the camera consists of three parts: the front panel, a lens insert and the lens itself.

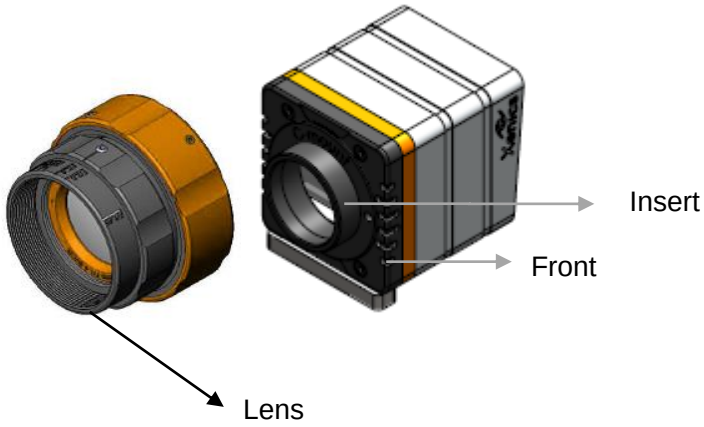

Figure 4-1 Optical components: lens – insert – front

A list of all possible lenses is shown in Table 4-1.

Lens configuration		Lynx GigE and CL
SWIR lens 12.5mm f/1.4	OPT-000106	x
SWIR lens 16mm f/1.4	OPT-000107	x
SWIR lens 25mm f/1.4	OPT-000108	x
SWIR lens 25mm f/2.1 for 25.6mm	OPT-000164	x
SWIR lens 35mm f/1.4	OPT-000109	x
SWIR lens 50mm f/1.4	OPT-000110	x
SWIR lens 50mm f/2.15 for 25.6mm	OPT-000184	x
SWIR lens 50mm f/2.0 + mount/filter holder	ASY-000657	x
SWIR lens 75mm f/2.0 + mount/filter holder	ASY-000443	x
SWIR lens 100mm f/2.0 + mount/filter holder	ASY-000444	x
SWIR lens 200mm f/2.4 + mount/filter holder	ASY-000658	x
C-mount extender rings	OPT-000119	x

Table 4-1 Lens configuration

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It is possible to use the following different solvents to clean a lens:

- Ethanol: removal of fingerprints and other contaminants
- Alcohol: final cleaning before use.

Perform the following steps to clean a lens:

1. Immerse lens tissue in Alcohol / Propanol or Ethanol (reagent grade).
2. Wipe the lens in "S" motion in such way that each lens area will not be wiped more than once!
3. Repeat stage 2 until the lens is clean. Use a new lens tissue each time!

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5. Electrical Interface

5.1. General Overview Connectors and Specifications

Connect all cables to the connectors at the rear side (see also (Ref 2)). Table 5-1 lists the connector and interface specifications overview for the Lynx-GigE and Lynx-CL.

Interface	Connector	Specification	Camera Protocol
XSL-GigE			
Input power (12V DC)	Hirose HR10-7R-4SA(73)	12V ±10%	
Trigger (either Trigger-in or Trigger-out!)	SMA	Trigger in: $V_{IN,L}$ = 0.8V Max. $V_{IN,H}$ = 2V Min. $V_{IN,MAX}$ = 30V Internal Pull-down: R = 10kΩ	
		Trigger out: V_{HIGH} = 3.3V ±10% V_{LOW} = 0V	
Ethernet	RJ45 connector	GigE standard	GigE Vision
XSL-CL			
Input power (12V DC)	Hirose HR10-7R-4SA(73)	12V ±10%	
Trigger (either Trigger-in or Trigger-out!)	SMA	Trigger in: $V_{IN,L}$ = 0.8V Max. $V_{IN,H}$ = 2V Min. $V_{IN,MAX}$ = 30V Internal Pull-down: R = 10kΩ	
		Trigger out: V_{HIGH} = 3.3V ±10% V_{LOW} = 0V	
Mini-camera link	CONN SDR 26POS VERT RECEPT	Serial control: 115200 baud, 8n1 Levels: RS-644	XSP Protocol: see (Ref 1)
		Image acquisition: CL	CL Base protocol/ 1 TAP for image acquisition

Table 5-1 Electrical interface specifications for Lynx-GigE and Lynx-CL cameras

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5.2. Power Interface

The power cable must be connected to the backside of the camera (see chap. (Ref 2) for its location). Table 5-2 lists the connector pins overview. Figure 5-1 shows schematically the pin location.

For the power cable (ASY-001268) the connector pins overview is shown in Table 5-3. Figure 5-2 shows schematically the pin location of the cable connector (Hirose HR10-7P-4P(73)).

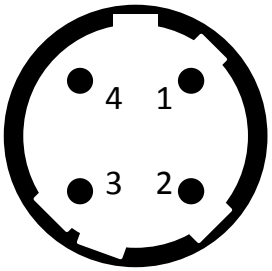

Figure 5-1 Camera power connector

Pin	Signal
1	+ 12V
2	+ 12V
3	Gnd
4	Gnd

Table 5-2 Camera power connector $12V_{DC}$

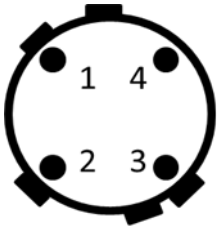

Figure 5-2 Cable connector

Pin	Signal
1	+ 12V
2	+ 12V
3	Gnd
4	Gnd

Table 5-3 Cable connector $12V_{DC}$

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5.3. Trigger Interface

Do not apply voltages to the trigger connector when it is configured in Trigger-OUT mode, because this will damage the camera!

For the trigger interface, a SMA connector is foreseen. The pin assignment is listed in Figure 5-3 Trigger interface pin assignment.

The trigger interface can be configured as **Trigger-IN** or **Trigger-OUT**. The following settings can be customized (see also (Ref 3)).

- Trigger OUT
  - Polarity:
    - High
    - Low.
  - Width
  - Delay.
- Trigger-IN
  - Source: frame or line trigger
  - Sensitivity
    - Level
    - Edge.
  - Polarity:
    - Low level / falling edge
    - High level / rising edge.
  - Delay
  - Trigger skip-count.

Pin	Signal	Cable
Shell	GND	Shield
Center	Trigger in	Inner conductor

Figure 5-3 Trigger interface pin assignment

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5.4. GigE Interface

GigE Vision® is a camera interface standard that uses the Gigabit Ethernet (GigE) communication protocol. It provides a framework for transmitting high-speed video and related control data over Ethernet networks.

To realize the GigE communication the Lynx-GigE cameras are equipped with a 1000Base-T Ethernet interface (RJ-45 connector). The data connection between camera and PC can be established via a standard CAT5e cable.

The GigE Vision standard defines how compliant products interact to deliver video and control information over Ethernet networks. It has the following four main elements:

- **Device discovery**: defines the sequence of events required for compliant devices to obtain valid Internet Protocol addresses, and for control applications to discover compliant devices.
- **GigE Vision control protocol (GVCP)**: defines how to specify video stream channels and control and configure compliant devices.
- **GigE Vision stream protocol (GVSP)**: defines how images are packetized and provides mechanisms for cameras or other types of video transmission systems to send image data and other information to compliant receivers.
- **An extensible mark-up language (XML) description file**: provides the equivalent of a computer-readable data sheet of features in compliant devices. This file must be based on standard defined by the European Machine Vision Association's GenICam™.

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5.5. Camera Link Interface

Camera Link is an interface for the transfer of digital video data. The standard defines data transfer on a physical base and determines connectors, cables and components for transmission and reception. Different configurations are available, distinguishing between the numbers of parallel transferred data bits.

For the Lynx-CL camera, the **BASE configuration with 1 TAP** is used. The pin lay-out and pin assignment of the Camera Link connector on the Lynx-CL camera are shown in Figure 5-4 and Table 5-4.

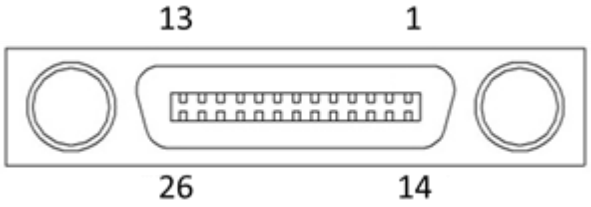

Figure 5-4 Pin out of Camera Link connector on the Lynx-CL camera

Pin	Signal	Pin	Signal
1	GND	14	GND
2	X0	15	X0+
3	X1	16	X1+
4	X2	17	X2+
5	XCLK	18	XCLK+
6	X3	19	X3+
7	SerTC+	20	SerTC-
8	SerTFG-	21	SerTFG+ P
9	CC1	22	CC1+
10	CC2+	23	CC2
11	CC3	24	CC3+
12	CC4+	25	CC4
13	GND	26	GND

Table 5-4 Camera Link connector (base) pin assignment

CC1 can be configured as line or frame trigger input (see also (Ref 3)).

CC2 to CC4 in Table 5-4 are not supported by the camera. The clock rate is 50 MHz with one tap & 16 bit/pixel.

i Info about the timing diagram can be found in (Ref 3).

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6. Software Installation

Before being able to start the camera, the Xeneth imaging suite (at least version 2.4) and its graphical user interface must be installed, so that the data coming from a wide variety of Xenics detectors and cameras can be easily operated on and analyzed.

6.1. Xeneth Installation

It is a good practice to first uninstall a previous Xeneth version when installing a new one.

Refer to the Xeneth Installation Manual (Ref 6) that is delivered on the CD together with the camera to install Xeneth.

When using camera link cameras, it is also necessary to pre-install the frame grabber before installing Xeneth! Refer to the National Instruments user manual of the frame grabber for installation instructions.

6.2. SDK Installation

When the SDK option was ordered, the SDK installation file is delivered on the CD together with the camera as well. Install the SDK software using this file.

After the SDK installation, the SDK manual, together with the samples and header files can be found in the C:\Program Files\Xeneth\SDK directory.

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7. Appendices

7.1. Appendix Xenics Serial Protocol

A detailed description of the Xenics Serial Protocol can be found in (Ref 1).

7.2. Appendix Mechanical Drawings

The complete mechanical drawing of the Lynx-GigE and Lynx-CL can be found in (Ref 2).

7.3. Appendix Control & Operation

The Control and Operation of XLIN 512-1024-2048 TE0 cameras and cores document lists the registers which are described in (Ref 3).

7.4. Appendix Frame Rate Calculator

The achievable frame rate and the minimal required frame time can be calculated using the Frame rate calculator sheet (Ref 4).

7.5. Appendix Network Connection Setup for GigE

The network connection set-up and the camera functions and features for Lynx-GigE are described in more detail in (Ref 5).

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